Deviation Firmware for Devo10 User's Manual

Version 2.0-Draft2

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Overview

Deviation is a replacement firmware for the Walkera Devo© series transmitters. The primary goal is to add support for multiple protocols, opening the full potential of this platform.

The core of the Deviation firmware is the mixer system, which is modeled after the system used in the Er9X firmware for the Turnigy/Flysky9x© transmitters.

Deviation also brings a USB file-system support, making it easy to manage the transmitter from any PC without the need for specialized upload/download tools.

Deviation has been designed for ultimate configurability. All model and transmitter configuration is controlled through text files which the firmware (or user) can read and write. It is easy to know exactly what is configured, as well as to modify the configuration either through the transmitter or with a text editor. The main screen is very configurable; any mix of inputs, switches, channel data, or timers can be displayed, and configured per-model. Deviation also supports customizable themes with full control over the images, fonts, and colors.

Deviation can store up to 255 different models, and uses a portable syntax that allows sharing models between any transmitter supported by Deviation.

Deviation has been internationalized. New language support can be added by simply copying a translation file into the appropriate directory on the transmitter.

Installation

Installation of Deviation is done just like upgrading the Walkera firmware. Note that Deviation will NOT overwrite Walkera models stored on the Tx. While they cannot be accessed by Deviation, they will be safely preserved should the Walkera firmware ever need to be reinstalled.

First install the deviation-x.yy.dfu firmware using the Walkera 'DfuSe USB Upgrade' tool. You will need the 'Devention DfuSe USB Upgrade Tool'from Walkera: <u>http://www.walkera.com/cn/soft_up/soft_file_1340783602848_null.zip</u>. **Do NOT attempt to use the DfuSe tool from STMicroelectronics!** It is recommended to test that this tool works by upgrading to a different Walkera firmware. Several users have had compatibility issues with the DfuSe tool.

Plug the transmitter into the PC via USB, and turn on the transmitter while holding 'EXT' to enter programming mode.

Available DFL	J Devices					
STM Device	in DFU Mode		•	DFU Mode Vendor ID	Product ID	Version
Supports	Upload Download] Manifestation] Accelerated	i Tolerant Upload (ST)	0483	DF11	0200
🗸 Can Deta	ch		()		Leav	/e DFU Mode
Firmware	Confi	g	Library			
– Upgrade Fi	ile					
File:			C:\devo8.dft	,		1
	File Information					
	Vendor ID	0483	Targets in File			
	Product ID	DF11	Firmware: 51			
	Version	0000				
Upload Action	n Upload		grade or Verify Action	n de 2	Upgrade	Verify
Transfered D 14	ata Size 8 KB(151872 Byte	s) of 148 KB(1	51872 Bytes)	Time Du	ration 00:00:31	
		F	ile correctly lo	aded.		
Abort]	de	evention DEVO-8 tr	ansmitter		Quit

- 1) Press the '...' button and select the dfu file to install
- 2) Select 'Upgrade' to install the firmware. This will be greyed-out if your Tx is not detected. Do NOT use 'Upload' as this will do nothing other than destroy the dfu file on your PC.

Turn off the transmitter, and turn back on while holding 'ENT'. There should be a USB logo on the screen.

If this is an upgrade from a previous Deviation release, it is strongly recommended to back-up the 'models' directory from the transmitter to ensure you don't lose any model configuration. Next unzip the deviation-lib-x.yy.zip to the PC and copy all directories EXCEPT for the 'models' directory to the transmitter. Optionally, copy the 'models' directory to the transmitter except for the currently configured model files. This last step will ensure that the defaults for newly created models have the latest options set.

If this is an upgrade from the Walkera firmware, the PC should prompt to format the drive. Format using default options. Next unzip the deviation-lib-x.yy.zip to the Tx USB drive.

USB & File-system

Deviation stores all configuration, bitmaps, and models as regular files on the USB filesystem.

USB can be most easily enabled by holding down the 'ENT' button while powering up the transmitter. Files can then be easily copied to or from the Tx.

5	
\tx.ini	Transmitter config. Includes trim settings, calibration data, and the last-used model number
\media\config.ini	The color scheme and fonts for the transmitter
\media\sound.ini	Contains notes to play for various alarms
\media*.bmp	Images used for the current Tx theme
\media*.fon	Font files
\models\default.ini	The default model, loaded whenever a model is cleared
\models\model*.ini	Configuration files for each model. Due to a limitation in the firmware, Deviation cannot create new files. It is therefore necessary to have a modelxx.ini for each model regardless of whether it is currently in use.
\modelico*.bmp	All available model icons (must be 52x36 pixels)
\templates*.ini	Configuration files used when loading predefined templates. These are nearly identical to the model configuration files, however they do not necessarily define all parameters
\language\lang*.*	Language translation files. These are UTF-8 text files con- taining the original English string and the respective trans- lated string

The directory structure is as follows:



Current Model: The name of the current model. It is configured from the Model Configuration page.

Transmitter Power: This indicates the currently selected transmitter power. It is configured from the Model Configuration page.

Battery Voltage: Numerical representation of current Tx battery state

Configurable Displays: These can be text-boxes contacting input, channel, or timer data; bar graphs displaying channel data; or icons displaying specific states (e.g. gear, flaps,...)

Model Icon: An image representing the current model. It is configured from the Model Configuration page.

Trims: The trim display can be configured to show either 4 or 6trims

Navigating

The transmitter menus can be navigated via the physical buttons (Up, Down, Left, Right, Ent, Ext).

The Menu is entered by pressing 'ENT' on the main menu

On all menu pages, 'UP' and 'DN' are used to navigate to the previous/next item. The 'R+' and 'L-' buttons are used on spin-box widgets to increase or decrease the selected value. In some cases holding down the button will use larger step values to move more quickly to the desired value.

For Buttons and rounded-spin-boxes, pressing ENT' will press the button Pressing 'EXT' will exit 1 menu level.

Menu Layout



Emulator

The emulator provides a side-screen displaying the current virtual-stick/switch states as well as the Channel output that would be received by the servos The emulator controls are as follows:

q/a	Throttle (Mode 2)	
Q/A	Left-Vertical trim	
w/s	Rudder (Mode 2)	
W/S	Left-Horizontal trim	
e/d	Elevator(Mode 2)	
E/D	Right-Vertical trim	
r/f	Aileron (Mode 2)	
R/F	Right-Horizontal trim	
Ζ	Gear	
X	Rudder Dual-Rate switch	
с	Elevator Dual-Rate switch	
V	Aileron Dual-Rate switch	
b	Mix 0/1/2 switch	
n	FMode 0/1/2 switch	
	Power off	
Left-arrow	Left	
Right-arrow	Right	
Up-arrow	Up	
Down-arrow	Down	
Enter	Ent	
Escape	Exit	

About Deviation Page

The Deviation release version can be accessed by selecting 'About Deviation' from the main menu. If it is ever necessary to report bugs with the Deviation firmware, include the version string found here with your report.

USB Page

The USB page cab be accessed by selecting 'USB' from the main menu. USB mode can then be toggled on/off to enable access to the transmitter's file-system. Note that doing so should never be done while the model is bound, as USB will disrupt signal transmission!

Transmitter Configuration Page

The Configuration page defines various transmitter functions. It is entered from the main menu via 'Transmitter Menu' followed by 'Transmitter Config'.



General Settings

Language: Select an appropriate language for all text Stick mode: Select one of Mode 1-4.

- Mode 1 is common in Europe. Elevator and Rudder on left, Throttle and Aileron on right.
- Mode 2 is common in North America. Throttle and Rudder on left, Elevator and Aileron on right.
- Mode 3 has Elevator and Aileron on left, Throttle and Rudder on right
- Mode 4 has Throttle and Aileron on left, Elevator and Rudder on right **Batt alarm**: Set battery voltage at which alarm will sound

Sticks: Calibrate the range of all analog sticks and dials

Buzz volume: Set buzzer volume

Vibration: Turn haptic feedback on/off

LCD Settings

Backlight: Set screen brightness Contrast: Set screen contrast Dimmer time: Set delay before screen dims Dimmer target: Set screen brightness when dimmed

Timer Settings

Prealert time: Time before timer reaches zero to start beeping **Prealert intvl**: How often to beep before timer reaches zero **Timeup intvl: How often to beep once timer has expired**

Telemetry Settings

Temperature: Set units to display temperature for telemetry **Length**: set units to display length for telemetry

Main Page Configuration

The Main Page Configuration page provides customized control of the main-page layout. The display of boxes, bars, icons, and trims along with their contents can all be controlled from here. This page is accessed from the main-menu via 'Model menu' followed by 'Main page config'.

Preview:	Long-Press E	NT
Trims:	4 Inside	
Box 1:	k Ch3	>
Box 2:	< Timer1	>
Box 3:	< Timer2	>

Preview

Entering preview by a long 'ENT' press will allow quickly visualizing any changes made via the configuration page. Press 'EXT' to return to the configuration.

Trim Positions

There are 3 options for the Trim Positions:

- 4 outside: Only 4 trims are shown, and they will be placed at the screen edges
- 4 inside: Only 4 trims are shown, and they are placed at the middle of the screen
- 6 Trims: 6 trims are shown., all placed towards the inside

Boxes

Boxes are used to display interesting text values. There are 8 available boxes. Boxes 1 through 4 are drawn on the left, and boxes 5 through 8 are drawn on the right. Currently a box can display one of the timers, one of the output channels, or telemetry data.

Switch Display

Switches are used to display the state of an input or output channel. A switch is either on (value > 0) or off (value <= 0). Up to 4 switches can be displayed. When a switch is enabled, a small indicator box will be displayed on the main page corresponding to the appropriate switch.

Quick-page Selection

Quick-pages allow quick access to other pages from the main page via Long-UP or LONG-DN buttons. Up to four quick-pages can be configured.

Mixer

The Mixer page controls how inputs (sticks/switches) are assigned to output channels. The mixer page is accessed from the main menu via 'Model menu' followed by 'Mixer'.



The Deviation mixer is modeled after the Er9x implementation. Each output channel is composed of a series of one or more mixers each of which consists of a single input, an activation switch, and a function/curve that modifies the mixer output. This is a very powerful capability, but it is requires a lot of understanding to make full use of. In order to simplify implementation, there are 3 templates that have been defined to make defining channels easier.

The number of channels available is dependent on the number of channels selected on the Model Setup Page. Additionally there are 10 Virtual channels that can be used as an intermediate step for complex setups (see Predefined Templates for an example)

Simple Template

The simple template is the simplest manner of defining a channel. It allows defining a primary-input (stick, switch, or other channel), and applying a curve or function to that input. The result can also be scaled or have an alternate zero-offset.



Src: The input source controlling this mixer

Curve: The function applied to the input to generate the output. See the Curve section for more info. Selecting the 'Curve' spin-box will allow configuring the Curve in the case that a multi-point curve or Expo-rate are chosen.

Scale: A multiplicative scalar that is applied after the Curve to control the output range Offset: an additive offset that is applied after the scaling.

Expo & Dual-Rate Template

The Expo/Dual-Rate template is a more sophisticated template designed to allow use of toggle or 3-way switches to manipulate an input. The primary-input (stick, switch, or other channel), can have a different curve/function and scaling for each toggleswitch position.



Selecting a value for Switch1 or Switch2 will activate the corresponding section. Each section can either have a 'linked' curve (curve is the same as the 'High Rate' curve) in which case only the scalar can be modified, or alternatively can have an independent

curve definition. Pressing the 'Mid-Rate' or 'Low Rate' button for a given switch will toggle between linked and independent curves.

Src: The input source controlling this mixer

Curve: The function applied to the input to generate the output. See the Curve section for more info. Selecting the 'Curve' spin-box will allow configuring the Curve in the case that a multi-point curve or Expo-rate are chosen.

Switch: Specify a switch to enable Medium or Low rates.

Scale: A multiplicative scalar that is applied after the Curve to control the output range

Complex Template

The Complex template unlocks the full power of the mixer system. For a given channel, any number of mixers can be applied to affect the final result. Each mixer is applied based on whether the specified switch is active, and can either replace, add to, or multiply to the



previous mixers for this channel. Using this system it should be possible to define an output channel as a combination of any number of inputs.

The Complex Mixer page has the following options:

Mixers: Specify the number of mixers for this channel

Page: Specify the current mixer page being edited. Pressing the spin-box will allow reordering the pages of the current channel.

Switch: Specify an optional switch which determines whether the current mixer is active. **Mux**: Defines how the current mixer is applied to the previously defined mixers for this channel. Options are:

- **Replace**: If this mixer is active, all previous mixers are ignored
- Add: Add the value of this mixer to the previous mixers
- Mult: Multiply the value of this mixer with the previous mixers
- Max: The output will be the greater of the current mixer vs the previous mixers
- Min: The output will be the lesser of the current mixer vs the previous mixers

Src: The input source controlling this mixer

Curve: The function applied to the input to generate the output. See the Curve section for more info. Selecting the 'Curve' spin-box will allow configuring the Curve in the case that a multi-point curve or Expo-rate are chosen.

Scale: A multiplicative scalar that is applied after the Curve to control the output range Offset: an additive offset that is applied after the scaling.

Trim: Selects whether or not any trims for the selected Source are applied to this mixer

Note that while the scale value is limited to 100%, the mixer may provide a value larger than 100% if an offset is set or if the trim value is non-zero.

A given mixer can be considered to have the general form: $M(x) = if(Switch) \{ Src * Curve * Scale + Offset \} else \{0\} + Trim$

The combination of mixers for a given output channel is defined by the Mux type:

For a 'Replace' mux: $Cx = if(Switch_n) \{M_n\}$ else if (Switch_{n-1}) $\{M_{n-1}\} \dots$ else if (Switch_0) $\{M_0\}$ For a 'Multiply' mux: $Cx = if(Switch_n) \{M_n\}$ else $\{1\} * if (Switch_{n-1}) \{M_{n-1}\}$ else $\{1\} * \dots *$ if (Switch_0) $\{M_0\}$ else $\{1\}$ For an 'Add' mux: $Cx = if(Switch_n) \{M_n\}$ else $\{0\} + if (Switch_{n-1}) \{M_{n-1}\}$ else $\{0\} + \dots +$ if (Switch_0) $\{M_0\}$ else $\{0\}$

For a 'Max' mux: $Cx = MAX(if(Switch_n) \{M_n\} else \{0\}, if (Switch_{n-1}) \{M_{n-1}\} else \{0\}, ..., if (Switch_0) \{M_0\} else \{0\})$

For a 'Min' mux: $Cx = MIN(if(Switch_n) \{M_n\} else \{0\}, if (Switch_{n-1}) \{M_{n-1}\} else \{0\}, ..., if (Switch_0) \{M_0\} else \{0\})$

Reordering Mixers

Since the ordering of mixers is important to the output, it is possible to reorder and/or copy mixers in order to facilitate building complex rules. This page is accessed by pressing the 'Page' spin-box on the complex mixer page.

Up (Dn)	Mixer 1
\langle Mixer 1 \rangle	Mixer 2
Copy To	Mixer 3
$\overline{+}$	Mixer 4
(Save)	

Select the respective mixer and use the up/down buttons to move the order of the selected mixer. Note that the mixer name represents its position when the reorder dialog was opened. If the dialog is closed and reopened, all mixers will be shown as numbered sequentially.

The reorder page can add new mixers or delete existing ones using the '+' and '-' buttons respectively. A mixer can also be copied to an existing mixer (overwriting it in the process) by using the 'Copy To' functionality

Available Curves

The following curve functions are supported: 1-to-1: Output is equal to the input (not editable). Fixed: Output is constant regardless of input (not editable). Min/Max: Output is -100 if input is < 0 and 100 if input is >= 0 (not editable) Zero/Max: Output is 0 if input is < 0 and 100 if input is >= 0 (not editable) >0: Output is 0 if input is < 0 and matches the input when >= 0 (not editable) <0: Output matches the input when < 0 and is 0 if input >= 0 (not editable) ABSVAL: Output is the absolute-value of the input (not editable) EXPO: Apply exponential curve to the input for non-linear response (editable) Deadband: Output will not respond to input values near zero (editable) Multi-point: Curve is based on 3 to 13user-defined points

Curve Editing

The Curve Editor is accessed by pressing a graph or by pressing the curve spin-box when it is selectable. Some curve types may not be edited (any of the curves preceding the 'Expo' curve), and the curve-box will not be selectable if one of these curves is currently active.

< EXPO >	(8	ave]
Pos/Neg:		/
<symmetric></symmetric>		\square
Value:		
< 75 >	/	

The Curve editor page will be difference depending on which curve is selected. It is not possible to change the curve type from the curve editor (except when a multi-point curve is selected)

For the Expo curve, the controls allow independently configuring the shape of the curve for values greater-than or less-than zero.

For the Deadband curve, the controls allow independently configuring the deadband width for values greater-than or less-than zero.

For the Multi-point curves, Each point can be individually set. Points are set by choosing the point number and then choosing a value. Touching the graph will allow quickly setting the value to the touched y-coordinate.

Channel configuration

The Channel configuration provides the ability to configure the final channel outputs. Capabilities such as channel reverse and failsafe-values are applied here. Also available are controls for end-points, scaling, sub-trim, and a safety switch (which could be used to ensure that a motor cannot spin-up while working on a model)

1-ELE		Revert		
Reverse:	۵	Normal		
Failsafe	€	Off	€	
Safety:	<	None	>	
Safe Val:		0		

Changes to this page will immediately effect the channel output. Pressing 'Revert' will restore the shown values to their saved state.

Reverse: Reverse the direction of servo rotation

Failsafe: Specifies a value that the Rx should use when it loses signal from the transmitter. Not all receivers support this capability.

Safety: Specifies a switch that will override all mixers and force the channel output to 'Value' when flipped.

Min/Max: These values define the minimum and maximum values that the transmitter will ever send to the receiver (after all scaling and trims are applied). If a calculated value is outside the min/max range, it will be clipped to either the min or max value as appropriate.

Scale: This is a final scalar to adjust the servo throw.

Sub-trim: Adjust servo zero position

Speed: Adjust maximum servo speed. Zero is disabled (fastest), 1 is slowest, 100 is fastest rate.

Trims and Virtual Inputs

The trim page allows assigning the trim buttons and trim step, as well as configuring buttons to work as virtual inputs. It s accessed from the main menu via 'Model menu' followed by 'Trims'.

Input:	Step:	Trim +:
THR	0.3	> TRIMLV+
(ELE) (0.1	> TRIMRV+
(RUD) <	0.1	> TRIMLH+
(AIL) <	0.1	> TRIMRH+

If the 'Input' field is set to an input stick, then the trim is applied as part of the mixer, and will operate as a typical trim control. If the 'Input' field is set as a channel or virtualchannel output, the value is applied directly to the channel output. In this case, the selected 'Pos' and 'Neg' buttons can operate as a virtual stick to control an output channel.

The Trim-step defines how sensitive the trims are to input. The maximum number of trim steps is +/-100. So a step size of 0.1 will allow a full +/-10% of trim adjustment on the servo.

Model Setup Page

The model page provides various model configuration options. It s accessed from the main menu via 'Model menu' followed by 'Model setup'.

Model setup	
File:	< Load 🌛
Model name:	(Modell)
Icon:	(Default)
Model type:	Heli →

File: The File spin-box allows loading a new model, copying the existing model to a new location, resetting the current model to the default (all configuration is lost), and loading templates (see Predefined Templates)

Model Name: Set the model's name

Icon: Choose the model's icon

Model Type: Set the model type. Some models (e.g. helicopter) have additional configuration options that can be accessed by clicking the Model type.

Protocol: Set the type of Rx being used. Note that some protocols have additional options that can be accessed by pressing the Protocol spin-box when it is active.

Number of channels: Sets the number of channels to transmit.

Tx Power: Specify the radio output power when applicable.

Fixed ID: The Fixed ID sets a unique code to ensure that the Tx will only bind to a specific model. This is useful to ensure that the Tx is not accidentally bound to the wrong model.

Bind: Depending on the protocol and Fixed-ID setting, the Tx may bind with the model on start-up, or may need to be manually bound once.

Protocol	Fixed ID = None	Fixed ID set
Devo	Bind on start-up	Manually bind with button
WK2801	Bind on start-up	Manually bind with button
WK2601	Bind on start-up	Bind on start-up
WK2401	Bind on start-up	Bind on start-up
DSM2	Manually bind with button	Manually bind with button
J6Pro	Manually bind with button	Manually bind with button
Flysky	Bind on start-up	Manually bind with button
Hubsan4	Bind on start-up	Bind on start-up
PPM	No binding	No binding

Protocol Options

Some protocols have customization values available.

Protocol: WK2601

Chan mode: Sets how channels are processed:

- 5+1: AIL, ELE, THR, RUD, GYRO (ch 7) are proportional. Gear (ch 5) is binary. Ch 6 is disabled
- Heli: AIL, ELE, THR, RUD, GYRO are proportional. Gear (ch 5) is binary. COL (ch 6) is linked to Thr. If Ch6 >= 0, the Rx will apply a 3D curve to the Thr. If Ch6 < 0, the Rx will apply normal curves to the Thr. The value of Ch6 defines the ratio of COL to THR.
- 6+1: AIL, ELE, THR, RUD, COL (ch 6), GYRO (ch 7) are proportional. Gear (ch 5) is binary. This mode is highly experimental.

COL Inv: Invert COL servo

COL Limit: Set maximum range of COL servo

Predefined Templates

The Deviation firmware supports usercustomizable predefined templates. By Selecting 'Template...' From the Model page, it is possible to select one of these options



Additional templates can be added via USB to the '\template' directory.

A template does not completely replace your existing model, but instead only a portion of it. The currently supported templates will replace the mixer and trim definitions, but will not affect the display layout. In the future Deviation will support templates that only affect the display layout without affecting the mixers as well.

Timer Page

The timer page defines the 2 available timers. Timers can count either up or down, and can be enabled either manually from the main screen or by an input trigger (stick or switch). This page is accessed from the main menu via 'Model menu' followed by 'Timers'.

Telemetry Configuration Page

The telemetry configuration page allows specifying alarms when specific telemetry events occur. This page is accessed from the main menu via 'Model menu' followed by 'Telemetry'

Telemetry config				
1 <	None	> <> => <		>
2<	None	> <>=> <		>
3<	None	> <>=> <		>
4 <	None	> <>=> <		>

Telemetry: Specify the telemetry input to use for alarm control. This can be a temperature probe, voltage probe, or RPM probe.

Equality: Can be '>=' or '<=' indicating whether a value above or below the target causes an alarm.

Target: The target value for the alarm